NVIDIA GH200 Grace Hopper Superchip Architecture

Performance and Productivity for Strong-Scaling HPC and Giant AI Workloads
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Inside NVIDIA’s First GPU-CPU Superchip

The NVIDIA® GH200 Grace Hopper architecture brings together the groundbreaking performance of the NVIDIA Hopper GPU with the versatility of the NVIDIA Grace™ CPU, connected with a high bandwidth and memory coherent NVIDIA NVLink Chip-2-Chip (C2C)® interconnect in a single Superchip, and support for the new NVIDIA NVLink Switch System.

NVIDIA NVLink-C2C is NVIDIA’s memory coherent, high-bandwidth, and low-latency interconnect for superchips. It is the heart of the Grace Hopper Superchip and delivers up to 900GB/s total bandwidth. This is 7x higher bandwidth than x16 PCIe Gen5 lanes commonly used in accelerated systems.

NVLink-C2C memory coherency increases developer productivity, performance, and the amount of GPU-accessible memory. CPU and GPU threads can now concurrently and transparently access both CPU and GPU resident memory, allowing developers to focus on algorithms instead of explicit memory management. Memory coherency allows developers to only transfer the data they need, and not migrate entire pages to and from the GPU. It also enables lightweight synchronization primitives across GPU and CPU threads by enabling native atomics from both the CPU and GPU. NVLink-C2C with Address Translation Services (ATS) leverages NVIDIA Hopper DMA engines for accelerating bulk transfers of pageable memory across host and device.

NVLink-C2C enables applications to oversubscribe the GPU’s memory and directly utilize NVIDIA Grace CPU’s memory at high bandwidth. With up to 480GB of LPDDR5X CPU memory per Grace Hopper Superchip, the GPU has direct high-bandwidth access to 6x more memory than available with PCIe. Combined with NVIDIA NVLink Switch System, all GPU threads running on up to 256 NVLink-connected GPUs on DGX GH200 can now access up to 144TB of memory at high bandwidth. Fourth generation NVLink allows
accessing peer memory using direct loads, stores, and atomic operations, enabling accelerated applications to solve larger problems more easily than ever.

NVIDIA GH200 Grace Hopper Superchip with HBM3 uses 96GB of HBM3 memory, delivering 4TB/s of memory bandwidth. The next generation NVIDIA GH200 Grace Hopper Superchip with HBM3e is the world’s first processor to utilize HBM3e memory technology and has 141GB of HBM3e delivering over 4.8TB/s, 1.5X more bandwidth than an H100 80GB SXM. The HBM in NVIDIA Grace Hopper is combined with the CPU memory over NVLink-C2C to provide up to 621GB of fast-access memory to the GPU to deliver the memory capacity and bandwidth required to handle the world’s most complex accelerated computing and generative AI workloads.

The NVIDIA GH200 Grace Hopper Superchip is the first true heterogeneous accelerated platform for high-performance computing (HPC) and AI workloads. It accelerates applications with the strengths of both GPUs and CPUs while providing the simplest and most productive heterogeneous programming model to date, enabling scientists and engineers to focus on solving the world’s most important problems. Together with NVIDIA networking technologies, NVIDIA GH200 provides the recipe for the next generation of HPC supercomputers and AI factories, enabling customers to take on larger datasets, more complex models, and new workloads, solving them more quickly than before.

This whitepaper highlights NVIDIA Grace Hopper’s key features, its programming model, and the performance improvements they deliver to the most demanding HPC and AI applications.

**NVIDIA GH200 Grace Hopper Overview**

NVIDIA Grace CPU is the first NVIDIA data center CPU, and it is built from the ground up to create HPC and AI superchips. The NVIDIA Grace CPU uses 72 Arm Neoverse V2 CPU cores to deliver leading per-thread performance, while providing higher energy efficiency than traditional CPUs. Up to 480GB of LPDDR5X memory provides the optimal balance between memory capacity, energy efficiency, and performance with up to 500GB/s of memory bandwidth per CPU. Its Scalable Coherency Fabric provides up to 3.2TB/s of total bisection bandwidth to realize the full performance of CPU cores, memory, system I/Os, and NVLink-C2C.

NVIDIA Hopper is the ninth-generation NVIDIA data center GPU and is designed to deliver order-of-magnitude improvements for large-scale AI and HPC applications compared to previous NVIDIA Ampere GPU generations. Thread Block Clusters and Thread Block Reconfiguration improve spatial and temporal data locality, and together with new Asynchronous Execution engines, enable applications to always keep all units busy.

NVIDIA GH200 fuses an NVIDIA Grace CPU and an NVIDIA Hopper GPU into a single superchip via NVIDIA NVLink-C2C, a 900GB/s total bandwidth chip-to-chip interconnect. NVLink-C2C memory coherency enables programming of both the Grace CPU Superchip and the Grace Hopper Superchip with a unified programming model.

NVIDIA Grace Hopper Superchip Architecture
Figure 1 shows the logical overview of the NVIDIA GH200 Grace Hopper Superchip and Table 1 lists its key features.

Figure 1. NVIDIA GH200 Grace Hopper Superchip Logical Overview

Table 1. NVIDIA GH200 Grace Hopper Superchip Key Features

<table>
<thead>
<tr>
<th>Feature</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Grace CPU cores (number)</td>
<td>Up to 72 cores</td>
</tr>
<tr>
<td>CPU LPDDR5X bandwidth (GB/s)</td>
<td>Up to 500GB/s</td>
</tr>
<tr>
<td>GPU HBM bandwidth (GB/s)</td>
<td>4TB/s HBM3</td>
</tr>
<tr>
<td></td>
<td>4.8TB/s HBM3e</td>
</tr>
<tr>
<td>NVLink-C2C bandwidth (GB/s)</td>
<td>900GB/s total, 450GB/s per direction</td>
</tr>
<tr>
<td>CPU LPDDR5X capacity (GB)</td>
<td>Up to 480GB</td>
</tr>
<tr>
<td>GPU HBM capacity (GB)</td>
<td>96GB HBM3</td>
</tr>
<tr>
<td></td>
<td>141GB HBM3e</td>
</tr>
<tr>
<td>PCIe Gen 5 Lanes</td>
<td>64x</td>
</tr>
</tbody>
</table>
NVIDIA GH200 Platforms

Heterogeneous GPU-CPU Platforms for AI, Data Analytics, and HPC

The GH200 Grace Hopper Superchip forms the basis for many different server designs that serve diverse needs in Machine Learning and HPC. NVIDIA has developed two platforms that address diverse customer needs.

- **NVIDIA MGX GH200** is ideal for scale-out of accelerated solutions including but not limited to traditional machine learning (ML), AI, data analytics, accelerated databases, and HPC workloads. With up to 621GB of fast memory, a single node can run a variety of workloads and when combined with NVIDIA Networking solutions (Connect-X7, Spectrum-X, and BlueField-3 DPUs), this platform is easy to manage and deploy, and uses a traditional HPC/AI cluster networking architecture.

- **NVIDIA DGX GH200** enables all GPU threads in the NVLink-connected domain to address up to 144TB of memory at up to 900GB/s total bandwidth per superchip, up to 450GB/s all-reduce bandwidth, and up to 115.2TB/s bisection bandwidth, in a 256 GPU NVLink connected system making this platform ideal for strong scaling the world’s largest and most challenging AI training and HPC workloads.

NVIDIA MGX GH200 with InfiniBand or Ethernet

Ideal for Scale-out Machine Learning and HPC Workloads

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Figure 2. NVIDIA MGX Platform
NVIDIA MGX is a modular reference architecture for accelerated computing. With it, ODMs and OEMs can use a building block approach to design multiple systems, saving development cost and time-to-market. NVIDIA MGX supports hundreds of GPU, DPU, CPU, storage, and networking combinations for AI, high-performance computing (HPC), and NVIDIA Omniverse™ workloads.

NVLink-connected domains are networked with NVIDIA InfiniBand (IB) or Ethernet networking, e.g., NVIDIA ConnectX-7 NICs paired with NVIDIA Quantum 2 NDR or NVIDIA Spectrum-4 switches, and/or OEM-defined I/O solutions.

Enhance MGX GH200 with NVIDIA BlueField-3 DPUs

Traditional supercomputing offers bare-metal performance without any isolation or secure infrastructure. The NVIDIA BlueField-3 Data Processing Unit (DPU) is a powerful “computer-in-front-of-a-computer” that is isolated and abstracted from the host system and therefore forms part of the trusted data center infrastructure. Bluefield DPUs deliver high-speed networking connectivity (using EDR, HDR, NDR InfiniBand, or 100/200/400G Ethernet) to connect nodes, in-network computing offloads for HPC, as well as infrastructure offload and acceleration. Together with the NVIDIA DOCA (Data center-on-a-Chip) framework, BlueField DPUs enable software-defined, hardware accelerated infrastructure and data center services for security (e.g., firewalls and data encryption), data protection, tenant isolation, and multi-tenancy on bare-metal environments. The DPUs also provide telemetry collection, storage virtualization, and system management functions that are fully isolated from the host, and therefore do not consume any CPU or GPU cycles.

Together, these technologies enable Cloud Native Supercomputing (CNSC), combining bare-metal performance and high data center efficiency with a modern zero-trust model for security isolation and multi-tenancy. CNSC includes storage virtualization for remote storage allocation as well as implementation of tenant Service Level Agreements (SLAs) such as rate-limiting, bandwidth-guarantees, and reservation of network resources based on tenant isolation and other requirements.

Advanced visibility is critical when operating at large-scale. NVIDIA BlueField-3 extends traditional monitoring tools by providing deep and instantaneous real-time visibility into every node. The NVIDIA DOCA Telemetry Service (DTS) is a containerized telemetry agent that supports collecting and exporting data from a wide range of providers at the operating system and network levels, including core and non-core Performance Monitoring Units, and the Baseboard Management Controller (BMC). This enables the characterization of user workloads and operators to detect and respond to system health and application performance issues and potential cyberattacks.

Figure 3 shows the MGX GH200 without NVLink Switch System. NVLink-C2C provides hardware coherency within a Grace Hopper Superchip. Each node contains one Grace Hopper Superchip and one or more PCIe devices like NVMe Solid-State Drives and BlueField-3 DPUs, NVIDIA ConnectX-7 NICs, or OEM-defined I/O. These nodes are designed for scale-out ML and HPC. With 16x PCIe Gen 5 lanes, an NDR400 InfiniBand NIC provides up to 100GB/s of total bandwidth across the Superchips.
The configuration in Figure 3 simplifies cluster management. It is designed for workloads that can leverage the strong compute capabilities of NVIDIA Grace Hopper and are not bottlenecked by the network communication overhead of InfiniBand, which is one of the fastest network interconnects available, but is still a traditional RDMA-accelerated network.

![Figure 3. NVIDIA MGX Grace Hopper Superchip system with InfiniBand networking for scale-out ML and HPC workloads](image)

**NVIDIA DGX GH200 AI Supercomputer**

**Ideal for strong-scaling giant AI LLM and Recommender Workloads**

NVIDIA DGX™ GH200 ushers in a new epoch in AI as a new class of AI supercomputer that fully connects 256 NVIDIA Grace Hopper™ Superchips into a singular GPU. Designed to handle trillion-parameter and terabyte-class AI models for massive recommender systems, generative AI, and graph analytics, DGX GH200 breaks through the memory constraints of a single accelerated system and offers a GPU memory space of up to 144 terabytes (TB), providing developers with nearly 500X more memory to build massive models.

The NVIDIA DGX GH200 with NVLink Switch System shown in Figure 4 enables each Hopper GPU to communicate with any other GPU in the NVLink domain at 900GB/s total bandwidth. NVLink TLBs enable a single GPU to address all the NVLink connected memory, that is, up to 144TB of memory for a 256-node NVLink connected system. Up to 256 Superchips can be connected using NVLink in a pod, and InfiniBand NICs and switches connect multiple superchip pods together. NVLink-C2C and the NVLink Switch System provide hardware consistency across all superchips within the NVLink-connected domain.

The high bandwidth and lower latencies of NVLink paired with memory consistency across all NVLink-connected GPUs and the ability to address up to 144TB of memory.
using direct loads, stores, and atomic operations, makes this system configuration ideal for strong-scaling machine learning and HPC workloads, and training giant AI models.

Figure 4. NVIDIA DGX GH200 with NVLink Switch System for strong-scaling giant ML workloads

NVIDIA MGX GH200 Comparisons

Table 2 compares the speeds and feeds of x86+Hopper, NVIDIA MGX GH200, and NVIDIA DGX GH200 with the NVLink Switch System, normalized by the number of Hopper GPUs in each system.

The NVIDIA MGX GH200 delivers 3.5x higher CPU memory bandwidth per GPU than x86+Hopper due to the 1:1 GPU to CPU ratio and the high LPDDR5X bandwidth of NVIDIA Grace CPU. NVIDIA Grace Hopper’s NVLink-C2C provides 7x higher GPU-CPU link bandwidth per GPU over PCIe Gen 5. The NVLink Switch System achieves up to 9x higher GPU to GPU total bandwidth than InfiniBand NDR400 NICs connected via x16 PCIe Gen5 lanes. This significant reduction in the amount of compute required to hide memory transfers makes the system easier to program and improves the performance of GPU-CPU bandwidth bound applications.
Table 2. NVIDIA MGX Grace Hopper Superchip vs. NVIDIA x86+Hopper

<table>
<thead>
<tr>
<th>Feature per GPU</th>
<th>HGX H100 4-GPU (x86)</th>
<th>NVIDIA MGX GH200 with HBM3</th>
<th>NVIDIA MGX GH200 with HBM3e</th>
<th>NVIDIA DGX GH200</th>
</tr>
</thead>
<tbody>
<tr>
<td>CPU Memory bandwidth (GB/s / GPU)</td>
<td>Up to 150</td>
<td>Up to 500</td>
<td>Up to 500</td>
<td>Up to 500</td>
</tr>
<tr>
<td>GPU Memory bandwidth (GB/s / GPU)</td>
<td>3000</td>
<td>4000</td>
<td>4800</td>
<td>4000</td>
</tr>
<tr>
<td>CPU Memory bandwidth to GPU</td>
<td>5%</td>
<td>12.5%</td>
<td>10.4%</td>
<td>12.5%</td>
</tr>
<tr>
<td>Memory bandwidth ratio</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>GPU-CPU Link bi-directional bandwidth (GB/s / GPU)</td>
<td>128 (x16 PCIe Gen5)</td>
<td>900 (NVLink-C2C)</td>
<td>900 (NVLink-C2C)</td>
<td>900 (NVLink-C2C)</td>
</tr>
<tr>
<td>GPU-GPU bi-directional bandwidth inter node (GB/s / GPU)</td>
<td>100 (InfiniBand NDR400)</td>
<td>100 (InfiniBand NDR400)</td>
<td>900 (NVLink 4 for dual GH200 with HBM3e)</td>
<td>100 (InfiniBand NDR400)</td>
</tr>
</tbody>
</table>

These improvements in CPU ratio, and NVLink-C2C and NVLink Switch System performance redefine how we achieve maximum performance from heterogeneous systems, enabling new applications, and efficient solutions to challenging problems.
NVIDIA GH200 Architecture

This section covers the main architectural features of the NVIDIA GH200 including: NVLink-C2C, NVLink Switch System, Extended GPU Memory (EGM), and the superchip flexible computing capabilities.

NVLink-C2C

The NVLink Chip-2-Chip (C2C) interconnect provides a high-bandwidth direct connection between a Grace CPU and a Hopper GPU to create the Grace Hopper Superchip, which is designed for drop-in acceleration of AI and HPC applications. With 900GB/s of bidirectional bandwidth, NVLink-C2C provides 7x the bandwidth of x16 PCIe Gen links at lower latency. NVLink-C2C also only uses 1.3 picojoules per bit transferred, which is greater than 5x more energy efficient than PCIe Gen 5.

Furthermore, NVLink-C2C is a coherent memory interconnect with native hardware support for system-wide atomic operations. This improves the performance of memory accesses to non-local memory, such as CPU and GPU threads accessing memory resident in the other device. Hardware coherency also improves the performance of synchronization primitives, reducing the time the GPU or CPU wait on each other, increasing total system utilization. Finally, hardware coherency also simplifies the development of heterogenous computing applications using popular programming languages and frameworks as elaborated in the NVIDIA Grace Hopper Programming Model section below.

NVLink Switch System in DGX GH200

NVIDIA NVLink Switch System combines fourth-generation NVIDIA NVLink technology with the new third-generation NVIDIA NVSwitch. A single level of the NVSwitch connects up to eight Grace Hopper Superchips, and a second level in a fat-tree topology enables networking up to 256 Grace Hopper Superchips with NVLink.

Fourth generation NVIDIA NVLink enables GPU threads to address up to 144TB of memory provided by all superchips in the NVLink network using normal memory operations, atomics, and bulk transfers. Communication libraries like MPI, NCCL, or NVSHMEM transparently leverage the NVLink Switch System when available.

NVIDIA NVLink Switch System connects each Grace Hopper Superchip to the network at 900GB/s total bandwidth. That is, a Grace Hopper Superchip pair exchanges data at up to 900GB/s. With up to 256 Grace Hopper Superchips, the network delivers up to 115.2TB/s all-to-all bandwidth. This is 9x the all-to-all bandwidth of InfiniBand NDR400, and 4.5x the all-reduce throughput.
The incredible one FP16 exaflop delivered by 256x Grace Hopper Superchips combined with the 115.2TB/s of all-to-all bandwidth provided by the NVLink Switch System and up to 144TB of directly addressable memory enables training giant AI models and strong scaling HPC and AI workloads.

Accelerating Applications with Extended GPU Memory

The NVIDIA GH200 is designed to accelerate applications with exceptionally large memory footprints, larger than the capacity of the HBM3 / HBM3e and LPDDR5X memory of a single superchip (see the NVIDIA GH200 Accelerated Applications section below).

The Extended GPU Memory (EGM) feature over the high-bandwidth NVLink-C2C enables GPUs to access all the system memory efficiently. EGM provides up to 144TBs system memory in a multi-node NVSwitch-connected system. With EGM, physical memory in the system can be allocated to be accessible from any GPU thread. All GPUs can access EGM at the minimum of GPU-GPU NVLink or NVLink-C2C speed.

Memory accesses within a Grace Hopper Superchip configuration go through the local high-bandwidth NVLink-C2C at 900GB/s total. Remote memory accesses are performed via GPU NVLink, and depending on the memory being accessed, also NVLink-C2C as shown in Figure 5. With EGM, GPU threads can now access all memory resources available over the NVSwitch fabric, both LPDDR5X and HBM3 or HBM3e, at 450GB/s.

Figure 5. Memory Accesses across NVLink-connected Grace Hopper Superchips

Flexible Architecture Built for Peak Performance

The NVIDIA Grace Hopper Architecture is flexible and enables applications ranging from large scale-out deep learning training and HPC workloads, to small inference workloads requiring Quality of Service (QoS).

The NVIDIA GH200 system can balance power between the NVIDIA Grace CPU and the Hopper GPU. The Grace Hopper Superchip enables building supercomputing systems
with a 1:1 GPU-CPU ratio that are power efficient and excel at GPU-heavy, CPU-heavy, and truly heterogeneous workloads. NVIDIA Grace Hopper nodes enable uniform systems to be built with higher peak performance, lower maintenance, and lower administration overheads.

The NVIDIA Grace CPU supports Memory Resource Partitioning and Monitoring (MPAM) features that provide performance isolation between jobs. MPAM enables users and administrators to partition the available LPDDR5X bandwidth and CPU cache usage. NVIDIA Multi-Instance GPU (MIG) allows partitioning of the Hopper GPU into smaller instances. Together MPAM and MIG can be used to partition system resources for improved QoS.

NVIDIA Grace Hopper Superchip Performance Monitoring Units (PMU) adhere to the ARM PMU architecture specification standards (Arm v8.5 PMUv3) for capturing performance metrics and are exposed via standard Linux performance tool interfaces like Linux perf. They provide a uniform and programmable approach for capturing performance metrics for the Grace CPU and Grace Hopper Superchip in a single pass. Single pass metric collection is performed at extremely low overhead with little CPU polling while supporting all features required for confidential computing. The metrics cover CPU core and caches, system caches, memory bandwidths, utilization, throughput, and latencies for GPU, CPU, NVLink-C2C, PCIe, and DRAM.
NVIDIA GH200 Programming Model

Traditional heterogeneous platforms with PCIe-connected accelerators require users to follow a complex programming model that involves manually managing device memory allocations and data transfer to and from the host.

The NVIDIA GH200 is a heterogeneous platform that is easy to program, and NVIDIA is committed to making it accessible to all developers, independent of their programming language of choice. Both the GH200 and the Platform are built to enable developers to pick the right language for the task at hand, and the NVIDIA libNVVM API enables developers to bring their preferred programming language to the CUDA platform with the same level of code-generation quality and optimizations as NVIDIA compilers and tools.

The languages provided by NVIDIA for the CUDA platform, as shown in Figure 6 include accelerated standard languages like:

- ISO C++
- ISO Fortran
- Python

And directive-based programming models like:

- OpenACC
- OpenMP
- CUDA C++
- CUDA Fortran

<table>
<thead>
<tr>
<th>Accelerated Standard Languages</th>
<th>Incremental Portable Optimization</th>
<th>Platform Specialization</th>
</tr>
</thead>
<tbody>
<tr>
<td>std::for_each(par, std::iota(n), [=](auto i) { y[i] += a*x; } );</td>
<td>#pragma acc data copy(x,y) { std::for_each(par, std::iota(n), [=](auto i) { y[i] += a*x; } ); }</td>
<td><strong>global</strong></td>
</tr>
<tr>
<td>do concurrent (i = 1:n) y(i) = y(i) + a*x(i) enddo</td>
<td>$!acc data copy(x,y) do concurrent (i = 1:n) y(i) = y(i) + a*x(i) enddo $!acc end data</td>
<td>void saxpy(int n, float a, float* x, float* y) { auto i = cg::grid_group::thread_rank(); if (i &lt; n) y[i] += a*x[i]; }</td>
</tr>
<tr>
<td>import cmumeric as np x = np.array(...) y = np.array(...) y += a*x</td>
<td>saxpy&lt;&lt;&lt;(n+255)/256,256,0&gt;&gt;(n, a, x, y); cudastreamsynchronize(s);</td>
<td></td>
</tr>
</tbody>
</table>

![Figure 6. NVIDIA GH200 Grace Hopper Superchip Programming Model](image)

NVIDIA is an important contributor to the ISO standardization processes of C++ and Fortran. We have worked together with these communities to enable ISO compliant C++ and Fortran applications to effectively program NVIDIA CPUs and NVIDIA GPUs without any language extensions.
This technology heavily relies on our hardware-accelerated memory coherency provided by NVIDIA NVLink-C2C and NVIDIA Unified Virtual Memory to lift the restriction of traditional PCIe-connected accelerated platforms.

On Linux systems with the Heterogeneous Memory Management (HMM) extension, the NVIDIA CUDA platform provides the same unified programming model as NVIDIA Grace Hopper. When running on NVIDIA Grace Hopper, these applications transparently benefit from the higher-bandwidth, lower-latency, higher atomic throughput, and hardware acceleration for memory coherency provided by NVLink-C2C.

Hardware Accelerated Memory Coherency

In PCIe-connected x86+Hopper systems, the CPU and the GPU have independent per-process page tables, and system-allocated memory is not directly accessible from the GPU (Figure 7). When a program allocates memory with the system allocator on the host, the page entry of the allocation is not available in the GPU’s page table and accessing it from GPU threads fails.

Figure 7. NVIDIA Hopper System with Disjoint Page Tables

In NVIDIA Grace Hopper Superchip-based systems, Address Translation Service (ATS) enables the CPU and GPU to share a single per-process page table, enabling all CPU and GPU threads to access all system-allocated memory (Figure 8), which can reside on physical CPU or GPU memory. The CPU heap, CPU thread stack, global variables,

\[\text{Equation}\]

1 Applications can lock the pages and register them with the CUDA driver using APIs like cudaHostRegister, but these API calls are expensive, they prevent memory migration, and the amount of pinned memory available is a scarce resource.

NVIDIA Grace Hopper Superchip Architecture
memory-mapped files, and inter-process memory are accessible to all CPU and GPU threads.

Figure 8. ATS in an NVIDIA Grace Hopper Superchip System

NVIDIA NVLink-C2C hardware-coherency enables the Grace CPU to cache GPU memory at cache-line granularity and for the GPU and CPU to access each other’s memory without page-migrations. NVLink-C2C also accelerates all atomic operations supported by the CPU and GPU on system-allocated memory. Scoped atomic operations are fully supported and enable fine-grained and scalable synchronization across all threads in the system.

The runtime backs system-allocated memory with physical memory on first touch, either on LPDDR5X or HBM3 / HBM3e, depending on whether a CPU or a GPU thread accesses it first. From an OS perspective, the Grace CPU and Hopper GPU are just two separate NUMA nodes.

System-allocated memory is migratable, i.e., the runtime can change its physical memory backing to improve application performance (Figure 9) or deal with memory pressure. Hardware access counters allow delayed migrations over a page-fault-based method so that only hot pages are migrated.
Figure 9. Access-Frequency-Based Automatic Memory Migration

Network and storage devices connected via non-coherent PCIe lanes have several methods for performing Direct Memory Access (DMA) and Remote DMA (RDMA) on system-allocated memory. On-Demand Paging (ODP) is an RDMA extension supported by NVIDIA InfiniBand Networking products like BlueField-3 and ConnectX-7 that allows devices to track pages being migrated. It enables communication and storage libraries such as MPI, HPC-X, NCCL, NVSHMEM, UCX, MAGNUM IO, and GPU Direct Storage to perform efficient zero-copy I/O operations on system-allocated memory without having to stage transfers through separate buffers.

CUDA-specific memory APIs provide users with guarantees about where the memory resides, which threads can access it, whether it is migratable, and many other features that enable users to extract all the performance the hardware has to offer. Applications can hint the system about their memory access patterns, for example, using CUDA and/or NUMA APIs, to enable the users to perform application-specific optimizations. NUMA memory hints enable applications to inform the runtime about their memory access patterns.

Memory Access in NVLink Switch System

On Grace Hopper Superchips connected with NVLink Switch Systems, GPU threads can address peer HBM3 / HBM3e and LPDDR5X memory from other Grace Hopper Superchips in the NVLink network via an NVLink page table (Figure 10). CUDA APIs allow applications to map memory from remote nodes into the current process and then perform load, stores, atomics, and as well as bulk memory transfers to directly access the memory.
Figure 10. GPU threads address peer memory from other superchips in the NVLink Switch network

NVIDIA CUDA Platform

The NVIDIA CUDA platform (Figure 11) is optimized for Arm CPUs, the NVIDIA Grace CPU, and of course, the NVIDIA GH200 and NVIDIA NVLink Switch System. NVIDIA CUDA is a comprehensive, productive, and high-performing platform for accelerated computing.

It accelerates end-user applications at all levels, from system software to application-specific libraries and frameworks, using all hardware available including GPUs, CPUs, DPsUs, and in-network computing (Figure 11). The CUDA platform has mature and user-friendly toolchains, developer tools, and documentation. It provides the best developer experience for accelerating applications on heterogeneous platforms.
Figure 11. NVIDIA CUDA Platform and its ecosystem

The NVIDIA Grace Hopper system is designed from the ground up to accelerate applications on the CUDA platform. Applications that run correctly on the NVIDIA Arm HPC developer kit continue to do so in Grace Hopper-based systems and immediately benefit from its memory coherent high-performance NVLink-C2C, NVLink Switch System, and high-bandwidth access to large amounts of memory.

NVIDIA is actively engaged with the broader developer community to ensure that the Arm ecosystem meets users’ requirements. The whole NVIDIA software stack is available for Arm server CPUs, including NVIDIA Grace CPU. Every CUDA component available on x86 today has Arm-native installers and containers. The NVIDIA GPU Cloud™ (NGC) provides DL, ML, and HPC containers optimized for Arm platforms.
Figure 12. Performance Simulations for GH200 with HBM3 vs x86+Hopper for end-user applications. Datasets and details described in the individual application section below.

NVIDIA GH200 Grace Hopper Superchip main architectural features are its NVLink-C2C interconnect, which provides memory coherency within the superchip enabling Extended GPU Memory (EGM), and NVLink Switch System which extends EGM beyond a single superchip. NVLink Switch System and NVLink-C2C are high-bandwidth and low-latency interconnects, providing up to 900GB/s total bandwidth when accessing up to 144TB of memory. NVIDIA Grace Hopper also provides a 1:1 GPU-to-CPU ratio, making the platform excel at GPU-heavy, CPU-heavy, and truly heterogeneous workloads that intensely engage both the GPU and the CPU.

This section highlights how these unique hardware features accelerate major applications shown in Figure 12, enable new applications, and improve developer productivity when writing new applications or incrementally accelerating already-existing ones on the GPU.

We highlight major algorithmic motifs like out-of-core processing, concurrent CPU and GPU processing, and applications with higher CPU performance requirements. We include examples within major fields like machine learning (natural language processing, recommender systems, Graph Neural Networks), databases, HPC (weather, climate, fluid dynamics, molecular dynamics, linear solvers), and the intersection of HPC with AI.
Inference for Large Language Models (LLM)

Higher CPU to GPU Bandwidth, MGX GH200 with HBM3

Inferencing for large language models requires a large memory capacity for storing model weights and intermediate results during the inference process. As the batch size of inference increases to accommodate growing demand of LLMs, the memory requirements also increase.

One way to address the memory requirements is to scale out to multiple GPUs or use CPU memory to offload parts of the model layers. With an x86 host CPU, accessing system memory for tensor offloading can become bottlenecks by PCIe. NVIDIA NVLink-C2C provides the Hopper GPU with high-bandwidth access to LPDDR5X memory. This significantly reduces the exposed tensor offloading execution time in the critical path and enables inference of LLMs at GPU throughput.

As shown in Figure 13, with batch size of 1, GH200 with HBM3 improves performance for LLM inference by 2x due to higher GPU memory bandwidth of H100 GPU in GH200 with HBM3 vs H100 PCIe GPU. As the batch size increases, the amount of memory required for inferencing also increases. At batch size 4, the performance of PCIe based inference solutions tanks as PCIe becomes the main bottleneck, however for GH200, the NVLink-C2C consistently feeds data to the H100 GPU at high bandwidth, delivering 4.5x throughput compared to the baseline PCIe solution.

![LLM Inference GPT-65B offload performance](image)

**Figure 13.** A performance simulation for LLM inference GPT3 65B LLM Model implemented with offloading.
Recommender Systems

Higher CPU to GPU Bandwidth and NVLink, DGX GH200

Modern recommender system models require substantial amounts of memory for storing embedding tables. Embedding tables contain semantic representations for items and users’ features, which help provide better recommendations to consumers. Generally, these embeddings follow a power-law distribution for frequency of use since some embedding vectors are accessed more frequently than others.

NVIDIA GH200 enables high-throughput recommender system pipelines that store the most frequently used embedding vectors in HBM3 memory, and the remaining embedding vectors in the higher-capacity LPDDR5X memory. The NVLink-C2C interconnect provides Hopper GPUs with high-bandwidth access to their local LPDDR5X memory, while the NVLink Switch System extends this to provide Hopper GPUs with high-bandwidth access to all LPDDR5X memory of all Grace Hopper Superchips in the NVLink network.

Figure 14 shows the performance improvement delivered by the DGX GH200 with NVLink Switch System over an equivalent x86+Hopper system for two Deep Learning Recommendation Model (DLRM) model sizes, 4.5TB (1.5x speedup, left) and 27TB (3.5x speedup, right).

For the 27TB large model, in both the x86+Hopper and NVIDIA Grace Hopper cases, most network communication is hidden behind the computations accessing the embedding tables. However, when the embedding computation is accelerated with NVLink-C2C, the communication must scale to avoid becoming the bottleneck. The NVLink Switch System on DGX GH200 accelerates all communication and achieves just that. For the smaller 4.5TB model, a significant part of communication is exposed on the x86+Hopper system. This communication gets accelerated over the NVLink Switch system on DGX GH200 when strong scaling to 128 GPUs.
Figure 14. A performance simulation for large DLRM network model with 4.5TB and 27TB model size, 128 GPUs, and embeddings offloaded to CPU memory.

Graph Neural Networks

Higher CPU to GPU Bandwidth, MGX GH200 with HBM3

Graph Neural Networks (GNNs) leverage message passing to extract information from data that is formed from individual nodes and their relation to each other, by repeatedly gathering information from neighboring nodes and transforming the aggregated representations. While this scheme is related to convolutional neural networks (CNNs) applied to image data, GNNs do so for arbitrary neighborhoods representing nodes in large networks of interactions at a large scale. GNNs therefore must cope with large datasets consisting of hundreds of millions of nodes and billions of edges. Besides the sheer scale of graph data, the arbitrariness of graph neighborhoods leads to irregular memory accesses to contiguous embedding tables and makes distributing the dataset across multiple GPUs challenging. Especially when data does not fit into the memory of a single GPU, or even of a single node.

We studied the performance of GraphSAGE, which is a model for node property prediction, with potential applications in biomedical contexts (e.g., drug discovery) or the financial service industry (e.g., fraud detection). To demonstrate the benefits of the CPU-GPU NVLink of Grace Hopper, we show the performance on an augmented version.
of the ogbn-products dataset having 626M nodes and 31B edges, coming to about 500GB in size.

NVIDIA GH200 with HBM3 accelerates GNN training with its high-bandwidth access to LPDDR5X through its NVLink-C2C interconnect. This allows large graph datasets to be stored in pinned memory and accessed efficiently. Our experiments show that Grace Hopper can provide 1.9x performance gains over x86+Hopper systems as shown in Figure 15.

![Normalized Execution Time Diagram]

Figure 15. A performance simulation shows normalized runtime per batch of a GraphSAGE model for an augmented ogbn-products dataset of 626 M nodes and 31 B edges.

Databases

**Higher CPU to GPU Bandwidth with Address Translation Service (ATS), MGX GH200 with HBM3**

Traditionally, GPU memory capacity limited the dataset sizes GPUs can operate on at high performance. Database workloads operate on exceptionally large input tables that
cannot fit in GPU memory, so performance is often limited by the CPU-GPU data transfer due to low PCIe bandwidth.

The Grace Hopper NVLink-C2C excels at databases, analytical workloads, and the Extract Transform Load (ETL) stages of ML applications. GPUs can now directly operate on datasets located in CPU memory at high speed, eliminating the PCIe bottleneck (Figure 16). Support for a rich set of atomic operations enables new coprocessing opportunities. For example, the CPU and the GPU can concurrently build a shared hash table for join and group by accessing both HBM3 and LPDDR5X.

Because GPUs can access all system-allocated memory, integrating GPU applications with pre-existing databases running on the CPU is easier than ever and provides performance benefits.

![Performance simulations for Hash Join with input tables in CPU Memory (left) and host-to-device transfer of pageable host-resident memory (right)](image)

Figure 16.

Large GPU database applications often need to process databases larger than the system memory capacity and strongly prefer to map those as pageable memory. On platforms without Address Translation Services (ATS), DMA transfers between CPU resident pageable memory must be staged through a host-pinned buffer for correctness: the pageable memory could be paged to disk, and this would cause the DMA to access the wrong physical memory. That is, the performance of host-to-device memory transfers on non-coherent platforms is limited by: \( \text{min} \ (\text{single-threaded CPU memcpy Bandwidth}, \text{PCIe Bandwidth}) \). The single-threaded CPU DRAM Bandwidth of modern CPUs is in the 20-40GB/s range and barely suffices to saturate PCIe Gen4 BW. PCIe Gen5 provides 64GB/s host-to-device bandwidth that these database applications cannot benefit from.

The ATS feature of the Grace Hopper Superchip enables the memory transfer accelerators to transfer pageable memory between the host and device without staging.
through a pinned memory buffer on the host using multiple CPU threads, or without pinning the memory buffer before the transfer using APIs like `cudaHostRegister`. With ATS, the performance of host-to-device memory transfers is limited only by the NVLink-C2C bandwidth between Grace and Hopper. The performance impact is projected in Figure 16 and highlights how applications transparently benefit from Grace Hopper features like ATS without any application-side changes.

The performance simulation for the Grace Hopper Superchip system with HBM3 uses the NVLink-C2C raw bandwidth. While the attainable bandwidth is often lower, it is not impacted by single-threaded CPU STREAM COPY Bandwidth.

**Partially Accelerated Applications**

**Higher CPU to GPU Bandwidth with Easier Incremental Porting, MGX GH200 with HBM3**

Multiphysics, quantum chemistry, and climate applications are large and complex. For example, weather and climate applications contain physical models for different phenomena like wind, clouds, distinct types of precipitation, evaporation, groundwater, solar radiation, ice, and oceans. Accelerating these applications with GPUs is an incremental and time-consuming process. Moving the entire application to GPU is often complicated and the performance benefits often diminish once the most computationally expensive modules are ported to the GPU.

The new unified NVIDIA Grace Hopper programming model presents opportunities for incremental porting of computationally expensive parts to the GPU, while leaving computationally inexpensive parts for the CPU to process, such as rarely used codes, or code that do not generate enough GPU work.

The NVIDIA Grace Hopper programming model enables the whole application to work on the same memory, simplifying incremental acceleration. At the same time, NVLink-C2C improves the performance of porting techniques, for example, redirecting BLAS library calls to NVBLAS.

**ABINIT** is a material science application that simulates Density Function Theory using standard BLAS calls. Figure 17 shows the performance impact of “drop-in” acceleration by executing standard BLAS calls on the GPU using NVBLAS. Because GPU threads access CPU memory at high bandwidth, porting techniques can avoid memory allocations and data transfer overheads. Grace CPU’s memory bandwidth and powerful compute performance deliver excellent performance to the parts of these applications that are better suited for CPUs, or not worth accelerating (see Table 1).
Figure 17. A performance simulation for ABINIT with NVBLAS featuring Titanium 255 Atoms using the LOBPCG algorithm.

OpenFOAM is a popular C++ toolbox for developing CFD and multiphysics solvers. When running on x86 CPUs, the pressure solver of OpenFOAM takes roughly 35% of the execution time of the OpenFOAM HPC Motorbike. After accelerating the pressure solver using AmgX and Hopper GPU, only 15% of the total runtime uses the GPU. The remaining 85% of the execution time is CPU-only and involves a mix of preprocessing, matrix assembly, and small linear solves.
Figure 18. A performance simulation for OpenFOAM HPC Motorbike L (34 M cells) on MGX GH200 with HBM3

The HPC Motorbike L case (a scaled-up version of the OpenFOAM Motorbike tutorial) is representative of typical engineering workloads, with a flatter profile and more time spent in turbulence calculations. The GPU portion of the code is still being optimized, but due to the substantial proportion of time spent in CPU-bound work, the Grace Hopper case provides significant speedup (Figure 18).

Molecular Dynamics: GROMACS

High-Bandwidth NVLink Switch System, DGX GH200

NVIDIA is a strong GROMACS contributor with an excellent track record in accelerating molecular dynamics simulations. Together with our collaborators, we have recently accelerated the Particle Mesh-Ewald (PME) implementation with multiple GPUs. It is expected to be available in the GROMACS 2023 release.

The implementation assigns one GPU to PME for every three or four GPUs assigned to PP. PME rank uses the NVIDIA accelerated multi-node FFT library, cuFFTMp, which is part of the NVIDIA HPC SDK, and is bottleneched by inter-node bandwidth. Historically, InfiniBand has been the fastest and most efficient external networking method to connect nodes and servers, but significant performance gains are possible by connecting all the nodes using NVLink.

NVIDIA Grace Hopper Superchip Architecture
Figure 19 compares the projected performance improvements of Grace Hopper systems with NVLink Switch System for GROMACS stmv benchmark with 1,066,628 atoms, against the performance of an MGX-H100 platform with InfiniBand HDR-200 network connections across nodes. Figure 19 (left) shows the normalized speedups of the different components of a PME time-step using 32 GPUs. FFT and PME-PME communication are sensitive to inter-node communication bandwidth and benefit from a 1.3x NVLink Switch System speedup. Figure 19 (right) shows the total normalized speedup for a varying number of GPUs.

Figure 19. Performance simulations for GROMACS stmv Benchmark on DGX GH200 with HBM3

For more details about GROMACS GPU implementation, see Pall et al. “Heterogeneous Parallelization and Acceleration of Molecular Dynamics Simulations in GROMACS” and the NVIDIA Technical Developer Blog articles by Gray et al. “Creating Faster Molecular Dynamics Simulations with GROMACS 2020” and “Maximizing GROMACS Throughput with Multiple Simulations per GPU Using MPS and MIG”.

Applications that perform FFTs are ideal candidates for being accelerated with Grace Hopper Superchip with NVLink Switch System. FFTs require high bandwidth all-to-all communications between GPU nodes. Figure 20 shows performance gains with Grace Hopper NVLink Switch System for FFTs of various sizes. It compares a Grace Hopper system with InfiniBand NDR400 versus a DGX GH200 system.
Figure 20. Speedup of DGX GH200 versus InfiniBand NDR400 on NVIDIA MGX GH200 with HBM3 for 3D FFTs of different sizes

Multi-Grid Linear Solvers

Easier CPU and GPU Coordination

Linear solvers are probably the most common tool in scientific computing applications. Multigrid iterative methods deliver linear complexity by solving problems at different resolutions and smoothing low-frequency errors using coarser grids (Figure 21).

The V-cycle (left) iteratively smoothens the error, propagating the residual to the coarsest grid (left, bottom). A direct solver computes the error at the coarsest level, and the V-cycle iteratively interpolates and smoothens it up to the finer grids (left, top). The F-cycle (right) accelerates the convergence with successively finer V-cycles, resulting in coarser grid solves than in the classical V-cycle.
Figure 21. GH200 Simplifies Multigrid Linear Solvers

Fine levels with many grid points run efficiently on throughput-oriented parallel architectures like GPUs. Coarse levels with few grid points are latency-limited on GPUs because they do not have enough work to utilize the available resources fully. A hybrid GPU-CPU scheme with a grid-size threshold ensures that coarse levels are executed on the latency-optimized Grace CPU (Figure 21 right).

When combined with adaptive mesh refinement and dynamic load balancing, data structures in multigrid solvers have deep hierarchies of pointers, and explicit data movement is challenging because of the indirect accesses. The NVIDIA Grace Hopper coherent programming model simplifies these applications and improves performance by allowing the GPU and CPU kernels to efficiently access all data and work on the same data structures without explicitly moving data around. This simplifies the implementation of switching between GPU and CPU kernels at a grid size threshold, while reducing the penalty for switching between processors, because both the GPU and CPU have fast access to system-allocated memory.
Appendix A: NVIDIA CUDA Platform

NVIDIA CUDA® is a comprehensive, productive, and high-performing platform for accelerated computing. It accelerates end-user applications at all levels, from system software to application-specific libraries and frameworks, using GPUs, CPUs, DPUs, and in-network computing. The CUDA platform has mature and user-friendly toolchains, developer tools, and documentation. It provides the best developer experience for accelerated heterogeneous applications.

CUDA System Software

The CUDA platform provides flexible system software components that help users deploy, manage, and optimize large heterogeneous systems productively and efficiently. The offering includes:

- Device drivers such as the CUDA driver
- Device management software such as NVML, NVIDIA System Management Interface, DCGM, and Unified Fabric Manager
- GUPDirect for heterogeneous network and file I/O
- Container-aware job-scheduling systems and operating systems such as DGX OS

High-Performance Libraries and Frameworks

NVIDIA Grace Hopper packs an immense amount of computing performance. A suite of heterogeneous libraries for compute-intensive applications complements the CUDA programming models to make this performance easily accessible. CUDA libraries maximize the performance of common math (CUDA Math Library), parallel algorithms (CUB and Thrust), linear algebra (cuBLAS), dense and sparse linear solvers (cuSOLVER and cuSPARSE), FFTs (cuFFT), random number generation (cuRAND), tensor manipulation (cuTENSOR), image and signal processing (NPP), JPEG decoding (nvJPEG), and GPU management (NVML). cuNumeric transparently accelerates and distributes NumPy programs to machines of any scale through Legate and the Legion runtime without any code modifications. libc++ provides heterogeneous synchronization and data-movement primitives to enable highly concurrent, heterogeneous, ISO-standard compliant C++ applications.

In addition, the CUDA platform communication libraries (Figure 11) enable standards-based scalable systems programming. HPC-X is a CUDA-aware MPI library with support for GUPDirect for sending and receiving GPU buffers directly using RDMA and GPU P2P. The NVIDIA Collective Communications Library (NCCL) implements highly optimized multi-node collective communication primitives. NVSHMEM is based on OpenSHMEM and provides heterogeneous multi-node communication primitives for both host and
device threads. cuFile and NVIDIA MAGNUM IO enable heterogeneous applications with high-performance file I/O through GPU Direct Storage.

An extensive suite of domain-specific libraries and frameworks further accelerates main algorithms in a wide range of application domains, for example:

- Deep neural networks (cuDNN)
- Linear solvers for simulations and implicit unstructured methods (AmgX)
- Quantum computing (cuQuantum)
- Data science
- Machine learning (RAPIDS)
- Data loading and preprocessing for machine learning (DALI)
- Real-time 3D simulation and design collaboration (Omniverse)

More than 150 Software Development Kits leverage these libraries to help developers become highly productive in a large set of application domains, including high-performance computing (NVIDIA HPC SDK), AI, Machine Learning, Deep Learning, and data science, genomics (NVIDIA CLARA), smart cities (NVIDIA Metropolis), autonomous driving (NVIDIA Drive SDKs), telecoms (NVIDIA Aerial SDK), robotics (NVIDIA Isaac SDK), Cybersecurity (NVIDIA Morpheus SDK), Computer Vision, and many more.

CUDA Profilers and Debuggers

The NVIDIA CUDA-GDB tool is an extension to GDB, the GNU Project debugger, and provides developers with a mechanism for debugging CUDA applications. The NVIDIA Compute Sanitizer is a functional correctness checking suite for highly concurrent CUDA kernels that precisely detects and attributes many common memory and thread safety errors like misaligned or out-of-bounds memory accesses, shared memory data races, uses of uninitialized memory, and invalid usages of synchronization primitives.

The NVIDIA Nsight™ family of performance analysis tools help users identify coarse- and fine-grained optimization opportunities in their applications. NVIDIA Nsight Systems is a system-wide performance analysis tool designed to visualize an application’s algorithms across many GPUs, CPUs, DPs, Memory, Network I/O, and File I/O. NVIDIA Nsight Systems is fully integrated with the CUDA ecosystem; supporting tracing, sampling, and visualizing system, library, and framework API calls, e.g., CUDA, CUDA-X, RAPIDS, Magnum-I/O, GPU Direct, MPI, UCX, OpenSHMEM, OpenMP, OpenACC, OS events, and even call-stack sampling. NVIDIA Nsight Compute is an interactive GPU kernel profiler that provides detailed performance and bottleneck analysis for optimizing single kernels towards peak GPU performance.

NVIDIA tools provide the same workflow experience on NVIDIA Grace CPU as on x86, and in addition support profiling and optimizing for the NVIDIA Grace Hopper architecture and its different single node and multi-node configurations.
NVIDIA profilers and debuggers are part of a larger tools and software ecosystem. Users should be able to use any tool they know and love on NVIDIA platforms. NVIDIA is a strong open-source contributor and Linux perf includes support for NVIDIA Grace Hopper Superchip Core and Uncore Performance Monitoring Units (PMUs), as well as ARM Statistical Profiling Extensions.

CUDA Documentation and Training

The large CUDA software ecosystem is complemented with excellent documentation for our programming models, for example, C++ parallel algorithms, libraries, libcu++, frameworks, RAPIDS AI, and SDKs, (HPC SDK).

The NVIDIA Deep Learning Institute (DLI) offers self-paced and live trainings, for example, at conferences like Supercomputing and the International Supercomputing Conference, that enable individuals to advance their knowledge in AI, accelerated computing, accelerated data science, graphics, simulation, and more. DLI trains and certifies qualified educators as DLI Ambassadors, at research institutions and HPC centers, enabling them to teach and tailor the DLI content to their needs.

Beyond our official documentation, NVIDIA partners with different communities and HPC sites to provide the GPU Hackathon and Bootcamp program. It pairs teams of domain scientists and research software engineers (RSEs) with GPU mentors from NVIDIA and the HPC community to transfer the software development, parallel computing, and optimization skills required to effectively use modern heterogeneous computing systems. Every year, NVIDIA holds its GPU Technology Conference (GTC) with a focus on educating developers on the latest NVIDIA platform and technology. The talks cover NVIDIA programming models, hardware details, and the applications of accelerated computing to a wide range of domains. All these talks are recorded and available at NVIDIA On-Demand.

CUDA Language and Compilers

The CUDA platform exposes a unified and flexible compiler stack for generating highly optimized device binaries through the NVIDIA NVVM IR and the NVIDIA libNVVM library. NVVM IR is a compiler Intermediate Representation (IR), based on LLVM-IR, providing a front-end compiler target for generating GPU compute kernels. libNVVM is a library for compiling and optimizing NVVM IR too, the virtual ISA of NVIDIA GPUs. All NVIDIA Compute compilers use libNVVM to target NVIDIA GPUs (Figure 22) and it enables users and frameworks to bring their programming language of choice to the CUDA platform with the same code generation quality and optimization as CUDA C++ itself.
Figure 22. Compiling high-level Languages to PTX with libNVVM

PTX, the portable virtual ISA of NVIDIA GPUs, is a public ISA targeted by third-party producers to run efficiently on our target architectures. PTX also has the advantages of being forward compatible and can be assembled offline or at runtime.

In many applications, the GPU compute kernels to be generated depend on the program inputs. While these applications could generate NVVM IR, the NVIDIA Runtime Compiler significantly improves the productivity of these applications and their users by allowing them to generate familiar CUDA C++ instead. NVRTC compiles CUDA C++, at runtime to PTX using libNVVM or to native GPU binary code by using an embedded PTX assembler as well. This enables applications, for example, Python programs, to dynamically generate kernels for the program a user input and C++ programs, to specialize compute kernels at runtime depending on program inputs.

The NVIDIA HPC SDK is a set of toolchains for heterogeneous systems. NVCC is a CUDA C++ compiler and the NVIDIA HPC compilers: NVC, NVC++ and NVFortran. These toolchains enable users to pick the right compiler toolchain that is best suited for their application.
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